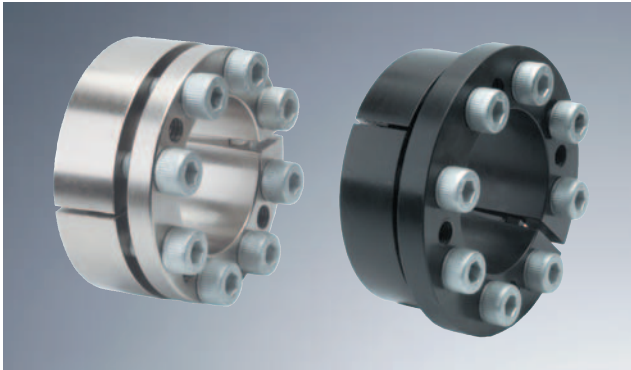
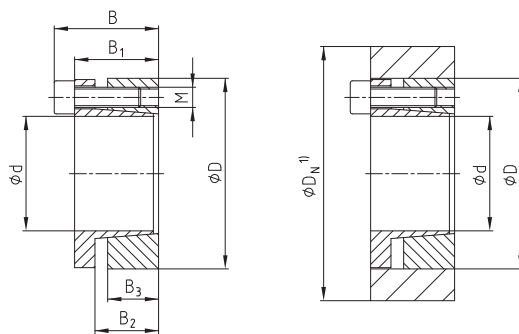


KTR 203 and KTR 206 (self-centering)



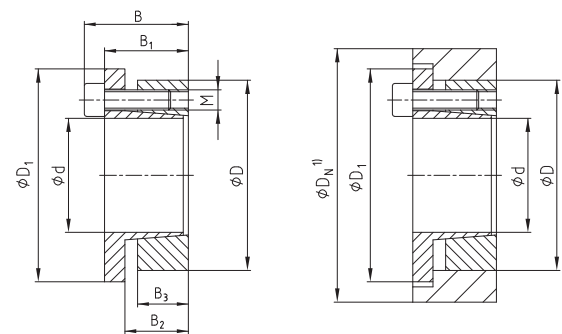
- Clamping set for universal applications
- Short dimensions
- Operation as with KTR 200/201
- Mounting instructions under www.ktr.com

KTR 203



Higher transmittable torque than KTR 206,
slight axial movement of the hub

KTR 206



No axial movement of the hub,
but lower transmittable torque than KTR 203

1) Dimension D_N : For calculation see page 282/283.

Assembly

Clean and lightly oil the contact surfaces of shaft and hub. Insert the clamping element into the hub fit and push it onto the shaft. Tighten the clamping screws crosswise, evenly and by degrees to the tightening torque T_A mentioned by means of the torque wrench. Check the tightening torque of all clamping screws in the order of arrangement. The figures T and F_{ax} mentioned in the table were calculated for an assembly with oil.

Note: Do not use any oil with molybdenum sulphide or high-pressure additions or grease reducing the coefficient of friction considerably. The clamping sets are delivered with oil. For assembly without oil the figures mentioned in the table deviate.

Disassembly

Unscrew the clamping screws. Screw the screws into the pull-off thread, tighten them crosswise by degrees and evenly until the rear taper ring is released. For repeated application oil the screws and threads.

Tolerances, surfaces

One accurate turning process is sufficient:

$$R_z \leq 16\mu\text{m}$$

Maximum permissible tolerances:

h8 for the shaft - H8 for the hub

Centering

The clamping elements KTR 203 and KTR 206 are **self-centering**. Between shaft and hub the concentricity of the clamping set is between **0,02** and **0,04** mm.

Order form:	KTR 203	40	x	65
	Type	Size of inside diameter		Size of outside diameter

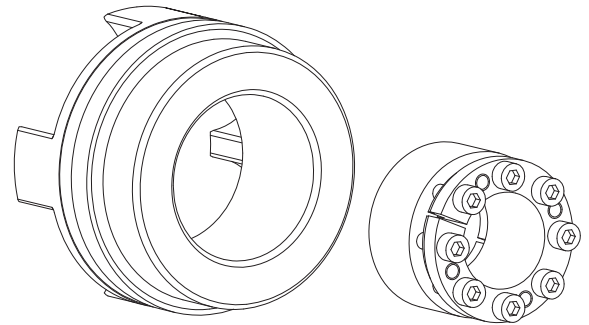
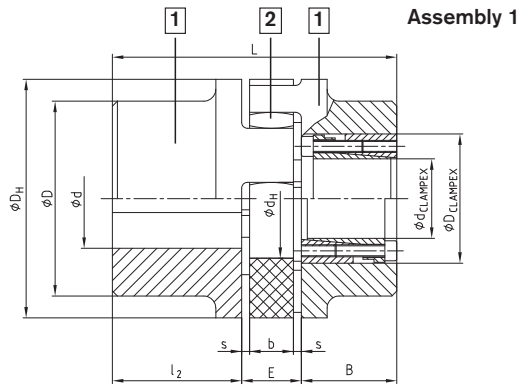
KTR 203 and KTR 206 (self-centering) – Technical Data

CLAMPEX® – KTR 203 and KTR 206																						
										KTR 203							KTR 206					
d x D [mm]	Dimensions [mm]					Clamping screws DIN EN ISO 4762 - 12.9 $\mu_{\text{total}}=0,14$					Transmittable torque or axial force		Surface pressure between clamping set		Weight [~kg]	Stock- programme	Transmittable torque or axial force		Surface pressure between clamping set		Weight [~kg]	Stock- programme
	B	B ₁	B ₂	B ₃	D ₁	M	z Number	T _A ¹⁾ [Nm]		T [Nm]	F _{ax} [kN]	Shaft P _W [N/mm²]	Hub P _N [N/mm²]	T [Nm]			F _{ax} [kN]	Shaft P _W [N/mm²]	Hub P _N [N/mm²]			
								KTR 203	KTR 206													
20 x 47	34	28	22	17	53	M6	6	14	17	428	43	334	142	0,25	●	332	33	259	110	0,26	●	
22 x 47	34	28	22	17	53	M6	6	14	17	471	43	304	142	0,23	●	366	33	236	110	0,24	●	
24 x 50	34	28	22	17	56	M6	6	14	17	514	43	278	134	0,26	●	399	33	216	104	0,27	●	
25 x 50	34	28	22	17	56	M6	6	14	17	535	43	267	134	0,25	●	415	33	207	104	0,26	●	
28 x 55	34	28	22	17	61,5	M6	6	14	17	599	43	239	121	0,31	●	465	33	185	94	0,32	●	
30 x 55	34	28	22	17	61,5	M6	6	14	17	642	43	223	121	0,29	●	499	33	173	94	0,30	●	
32 x 60	34	28	22	17	67	M6	8	14	17	913	57	278	148	0,34	●	709	44	216	115	0,35	●	
35 x 60	34	28	22	17	67	M6	8	14	17	999	57	254	148	0,33	●	776	44	198	115	0,34	●	
38 x 65	34	28	22	17	72	M6	8	14	17	1084	57	234	137	0,38	●	842	44	182	106	0,39	●	
40 x 65	34	28	22	17	72	M6	8	14	17	1141	57	223	137	0,34	●	886	44	173	106	0,35	●	
42 x 75	41	33	25	20	84	M8	8	35	41	2207	105	332	186	0,59	●	1719	82	259	145	0,60	●	
45 x 75	41	33	25	20	84	M8	8	35	41	2364	105	310	186	0,58	●	1842	82	241	145	0,59	●	
48 x 80	41	33,5	24	20	89	M8	8	35	41	2522	105	290	174	0,64	●	1965	82	226	136	0,65	●	
50 x 80	41	33,5	24	20	89	M8	8	35	41	2627	105	279	174	0,63	●	2047	82	217	136	0,64	●	
55 x 85	41	33,5	24	20	91	M8	8	35	41	2890	105	253	164	0,69	●	2252	82	197	128	0,70	●	
60 x 90	41	33,5	24	20	99	M8	8	35	41	3152	105	232	155	0,73	●	2456	82	181	121	0,74	●	
65 x 95	41	33,5	24	20	104	M8	8	35	41	3415	105	214	147	0,79	●	2661	82	167	114	0,80	●	
70 x 110	50	40	29	24	119	M10	8	70	83	5934	170	268	170	1,47	●	4550	130	205	131	1,58	●	
75 x 115	50	40	29	24	124	M10	8	70	83	6358	170	250	163	1,55	●	4875	130	192	125	1,66	●	
80 x 120	50	40	29	24	129	M10	8	70	83	6782	170	234	156	1,65	●	5200	130	180	120	1,77	●	
85 x 125	50	40	29	24	134	M10	10	70	83	9007	212	276	187	1,72	●	6907	163	211	144	1,84	●	
90 x 130	50	40	29	24	139	M10	10	70	83	9537	212	260	180	1,81	●	7313	163	200	138	1,94	●	
95 x 135	50	40	29	24	144	M10	10	70	83	9611	202	235	166	1,90	●	7501	158	184	129	2,03	●	
100 x 145	56	44	31	26	154	M12	8	115	145	11719	234	239	165	2,48	●	9465	189	193	133	2,68	●	
110 x 155	56	44	31	26	164	M12	8	115	145	12891	234	217	154	2,66	●	10411	189	176	125	2,86	●	
120 x 165	56	44	31	26	174	M12	9	115	145	15821	264	224	163	2,84	●	12777	213	181	132	3,06	●	
130 x 180	64	52	39	34	189	M12	12	115	145	22853	352	211	152	4,45	●	18456	284	170	123	4,69	●	
140 x 190	68	54	39	34	199	M14	9	185	230	25699	367	205	151	4,62	●	20453	292	163	120	4,94	●	
150 x 200	68	54	39	34	209	M14	10	185	230	30595	408	212	159	4,80	●	24349	325	169	127	5,14	●	
160 x 210	68	54	39	34	219	M14	12	185	230	39161	490	239	182	5,18	●	31167	390	190	145	5,54	●	
170 x 225	78	64	49	44	234	M14	12	185	230	41609	490	225	170	7,33	●	33115	390	179	135	7,71	●	
180 x 235	78	64	49	44	244	M14	12	185	230	44056	490	212	163	7,77	●	35063	390	169	129	8,17	●	

● Clamping sets available from stock.

1) These are the maximum screw tightening torques. They can be reduced to max. 40% of the aforementioned figures with T, F_{ax}, P_W and P_N being reduced proportionally.

KTR 200 with torsionally flexible ROTEX® coupling



Assembly 2

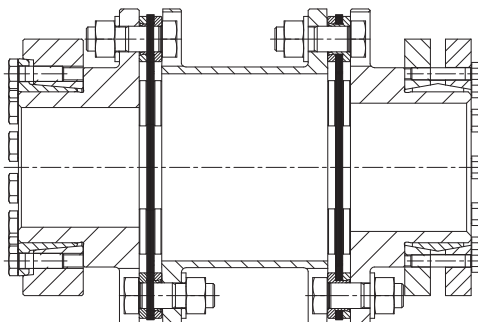
KTR 200 with torsionally flexible ROTEX® coupling															
ROTEX® size	Pilot bore ϕd [mm]	Hub material	Dimensions of CLAMPEX® KTR 200 [mm]					Dimensions of ROTEX® coupling [mm]							
			Maximum KTR clamping $d \times D$	Transmittable torques and axial force		B	l_1	E	s	b	D_H	D	D_1	d_H	L
				T [Nm]	F_{ax} [kN]										
42	x	Steel part 1	30 x 55	769	51	48	50	26	3,0	20	95	-	95	46	Length L > $l_1 + E + B$ (clamping set)
48	x		35 x 60	1197	68	48	56	28	3,5	21	105	-	105	51	
55	x		45 x 75	2132	95	59	65	30	4,0	22	120	-	120	60	
65	x		45 x 75	2132	95	59	75	35	4,5	26	135	115	-	68	
75	x		50 x 80	3159	126	59	85	40	5,0	30	160	135	-	80	
90	x	GGG 40 part 1	65 x 95	4107	126	59	100	45	5,5	34	200	160	-	100	
100	45		65 x 95	4107	126	59	110	50	6,0	38	225	180	-	113	
110	58		70 x 110	7023	201	70	120	55	6,5	42	255	200	-	127	
125	58		80 x 120	8026	201	70	140	60	7,0	46	290	230	-	147	
140	56		95 x 135	11373	239	66	155	65	7,5	50	320	255	-	165	
160	78		110 x 155	16068	292	80	175	75	9,0	57	370	290	-	190	
180	80		120 x 135	21910	365	80	195	85	10,5	64	420	325	-	220	

CLAMPEX® – KTR 200																	
d x D [mm]	B [mm]	Transmittable torques and axial force		Clamping screws DIN EN ISO 4762 12.9 [mm]		d x D [mm]	B [mm]	Transmittable torques and axial force		Clamping screws DIN EN ISO 4762 12.9 [mm]		d x D [mm]	B [mm]	Transmittable torques and axial force		Clamping screws DIN EN ISO 4762 12.9 [mm]	
		T [Nm]	F _{ax} [kN]	z x M	T _A [Nm]			T [Nm]	F _{ax} [kN]	z x M	T _A [Nm]			T [Nm]	F _{ax} [kN]	z x M	T _A [Nm]
20 x 47	48	513	51	6 x M6	17	38 x 65	48	1299	68	8 x M6	17	65 x 95	59	4107	126	8 x M8	41
22 x 47	48	564	51	6 x M6	17	40 x 65	48	1368	68	8 x M6	17	70 x 110	70	7023	201	8 x M10	83
24 x 50	48	616	51	6 x M6	17	42 x 75	59	1990	95	6 x M8	41	75 x 115	70	7524	201	8 x M10	83
25 x 50	48	641	51	6 x M6	17	45 x 75	59	2132	95	6 x M8	41	80 x 120	70	8026	201	8 x M10	83
28 x 55	48	718	51	6 x M6	17	48 x 80	59	3033	126	8 x M8	41	85 x 125	70	10659	251	10 x M10	83
30 x 55	48	769	51	6 x M6	17	50 x 80	59	3159	126	8 x M8	41	90 x 130	70	11286	251	10 x M10	83
32 x 60	48	1094	68	8 x M6	17	55 x 85	59	3475	126	8 x M8	41	95 x 135	66	11373	239	10 x M10	83
35 x 60	48	1197	68	8 x M6	17	60 x 90	59	3791	126	8 x M8	41	Further details see page 263.					

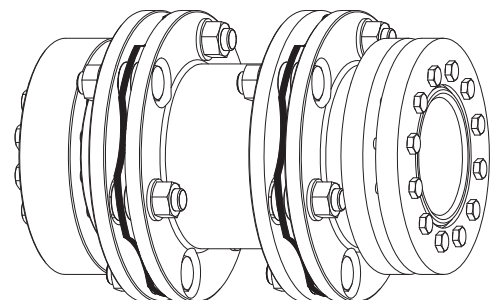
Other coupling combination

RADEX®-N NANA 1 with external clamping set KTR 620 and KTR 603

KTR 620



KTR 603



Further details about the external clamping set KTR 620 and KTR 603 are shown on page 254-259.

Calculation

For a properly working CLAMPEX® shaft-hub-connection the following technical details should be taken into account. Please contact us in case you have tolerances different from the table below.

CLAMPEX® – Toleranzen, Rautiefe und Rundlaufgenauigkeit						
Type	d [mm]	d _w [mm]	Shaft diameter tolerance	Diameter of hub bore tolerance	Surface roughness [μm]	Concentricity (applies for the clamping set only)
KTR 250	-	-	h8	H8	Rz ≤ 16	0,02 - 0,04
KTR 200	-	-	h8	H8	Rz ≤ 16	0,02 - 0,04
KTR 201	-	-	h8	H8	Rz ≤ 16	0,02 - 0,04
KTR 203	-	-	h8	H8	Rz ≤ 16	0,02 - 0,04
KTR 206	-	-	h8	H8	Rz ≤ 16	0,02 - 0,04
KTR 225	-	-	h8	H8	Rz ≤ 16	0,02 - 0,04
KTR 100	-	-	h11	H11	Rz ≤ 16	1)
KTR 105	-	-	h9	H9	Rz ≤ 16	0,02 - 0,04
KTR 150	up to 38	-	h6	H7	Rz ≤ 6	1)
KTR 150	bigger than 38	-	h8	H8	Rz ≤ 6	1)
KTR 400	-	-	h8	H8	Rz ≤ 16	0,02 - 0,04
KTR 620	-	13-150 > 160	H7/h6 > H7/g6	H7/f7	Rz ≤ 16	0,02 - 0,04
KTR 603	-	18 - 30	j6	H6	Rz ≤ 16	0,02 - 0,04
KTR 603	-	31 - 50	h6	H6	Rz ≤ 16	0,02 - 0,04
KTR 603	-	51 - 80	g6	H6	Rz ≤ 16	0,02 - 0,04
KTR 603	-	81 - 500	g6	H7	Rz ≤ 16	0,02 - 0,04

1) Depending on the centering of the hub or shafts or the drive component and accuracy of assembly, respectively.

Fatigue strenght and shape stability of components loaded under torsion and bending

The stress calculation figures β_k for the clamping elements, are worked out similar to those of hydraulic fittings. Please contact us for calculations. The stress concentration is dependet upon the load, the material and the clamping set type. Stress concentration factor on request.

Resulting torque T_R

The transmittable torque $T \approx T_R$ always has to exceed the highest torque peak T_B which may arise in the connection positions. The torque peaks arising during the acceleration of electric motors have to be considered.

$$T \approx T_R \geq \sqrt{T_B^2 + \left[\frac{F_a \cdot d}{2} \right]^2} \quad [\text{Nm}]$$

Transmittable axial force F_{ax}

The maximum transmittable axial force F_{ax} which is mentioned in the tables has to be reduced accordingly in case of additional torque transmission.

$$F_{ax} = \frac{2 \cdot T}{d} \quad [\text{kN}]$$

Calculation of the outside diameter of the hub D_N

The required outside diameter of the hub D_N depends on the cross section of the hub, the shape of the hub and the apparent yield point of the hub material. In order to facilitate the calculation the table on page 283 shows some figures by the help of which D_N can be determined.

Example:

Shaft diameter $d = 50 \text{ mm}$
Hub material: GGG 40
Apparent yield point of material
 $\sigma_{0,2} = 250 \text{ N/mm}^2$

Selected: CLAMPEX® clamping set KTR 100

with $d \times D = 50 \text{ mm} \times 80 \text{ mm}$ and $P_N = 149 \text{ N/mm}^2$ page 277
→ approximate value from table on page 283: $P_N = 150 \text{ N/mm}^2$
selected design see page 283. $C = 0,8$ (value C of hub shape)
→ figure as per table 1,69
→ $D_N = D \times 1,69 = 80 \text{ mm} \times 1,69 = 135,20 \text{ mm}$

Outside diameters of hubs which cannot be calculated based on the table are calculated with the following formula:

$$D_N \geq D \cdot \sqrt{\frac{\sigma_{N0,2} + P_N \cdot C}{\sigma_{N0,2} - P_N \cdot C}} \quad [\text{mm}]$$

Tangential tension on the inside diameter of hub

$$\sigma_{tiN} \approx P_N \frac{(1 + C_N^2)}{(1 - C_N^2)} \cdot C \quad [\text{N/mm}^2]$$

For clamping connections with hollow shafts the required inside diameter of the hollow shaft d_{iW} is calculated with the following formula:

$$d_{iW} \leq d \cdot \sqrt{\frac{\sigma_{W0,2} - 2 \cdot P_W \cdot 0,8}{\sigma_{W0,2}}} \quad [\text{mm}]$$

Tangential tension on the inside diameter of shaft

$$\sigma_{tiW} \approx \frac{2 \cdot P_W}{(C_W^2 - 1)} \quad [\text{N/mm}^2]$$

$\sigma_{N0,2}$ = Apparent yield point of the hub material [N/mm²]
 C = Value C of hub shape (see picture on page 283)
 P_N = Perm. surface pressure of clamping set/hub [N/mm²]
 D = Outside diameter of the clamping set [mm]
 T = Transmittable torque [Nm]
 T_R = Resulting transmittable torque [Nm]
 T_B = Operating torque to be transmitted [Nm]
 L/L_1 = Hub length [mm]

$\sigma_{W0,2}$ = Apparent yield point of the shaft material [N/mm²]
 P_W = Perm. surface pressure of clamping set/shaft [N/mm²]
 d = Inside diameter of the clamping set [mm]
 C_W = d_{iW} / d
 C_N = D / D_N
 F_a = Axial force arising during operation [N]
 F_{ax} = Maximum transmittable axial force [kN]
 F_V = Prestressed force [N]

